**[[1]](#footnote-1) Transformed Data Obtained by Ensemble Clustering-Classification and Reduction**

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**Abstract**

The performance of many supervised or unsupervised machine learning algorithms depends very much on distance metrics to determine similarity between data points. A suitable distance metric could improve the classification performance, and clustering process significantly.

Distance metrics over a given range of data should reflect the actual similarity between objects. One of the obvious weaknesses of the Euclidean distance is dealing with data that is represented by a large number of attributes, where the Euclidean distance does not capture the actual relationship between those points. However, objects belonging to the same cluster usually share some common traits even though their Euclidean distance might be relatively large.

In this study, we propose a new classification method named *GrbClassifierEC* that replaces the given data space with categorical space based on ensemble clustering (EC). The similarity between objects is defined as the number of times that the objects belong to the cluster. The EC space is defined by tracking the membership of the points over multiple runs of clustering algorithms. Different points that were included in the same clusters will be represented as a single point. Our algorithm classifies all these points as a single class(\*\*we mean we assign those points to be belongs to one class, mainly we have two-class data\*\*). In order to evaluate our suggested method, we compare its results to the *k* nearest neighbors, Decision tree and Random forest classification algorithms on several benchmark datasets. The results confirm that the suggested new algorithm *GrbClassifierEC* outperforms the other algorithms.

*Keywords*—Decision trees, Ensemble clustering, Classification.

# **INTRODUCTION**

T

his research presents a new classification model which classifies objects after running a mapping procedure that replaces a given data space with categorical space based on ensemble clustering (EC).

The main assumption in this research is that points belonging to the same cluster are more similar to other points from other clusters even though their Euclidean distance is closer. This is because the clustering algorithms take into account both the geometric space as well as other statistical parameters.

In this research we propose a procedure that transforms the original data space to another categorical feature space based on clustering algorithms. We call the new space EC space.

In general, the EC algorithm runs multiple clustering algorithms several times with different parameter values. Each data point is represented by the labels of the clusters it belongs to in each iteration yielding a categorical space. As a result, two different points may be represented identically if they were in the same clusters in each iteration. All the points that fall in the same cluster in the different clustering runs define an identical group and will be presented by a representor. Our algorithm classifies only the representors, and all the group members will have the same class label.

In our experiments we use the *k-means* clustering algorithm with different *k* values. We can see that not only the number of the data points (size) decreased, but also the number of features. This reduction is different than traditional feature reduction that eliminates some of the unneeded features. In the proposed new method we represent the data differently by clustering results.

Combination clustering is a more challenging task than the combination of supervised classifications. Topchy et al [1] and Strehl et al [2] addressed this issue by formulating consensus functions that avoid an explicit solution to the correspondence problem. Recent studies have demonstrated that consensus clustering can be found using graph-based, statistical or information-theoretic methods without explicitly solving the label correspondence problem as mentioned in [3]. Other empirical consensus functions were also considered in [4][5][6].

A clustering-based learning method was proposed in[7]. In this study, several clustering algorithms are run to generate several (unsupervised) models. The learner then utilizes the labeled data to guess labels for entire clusters (assuming that all points in the same cluster have the same label). In this way, the algorithm forms a number of hypotheses. The one that minimizes the PAC-Bayesian bound is chosen and used as the classifier. The authors assume that at least one of the clustering runs will produce a good classifier and that their algorithm will find it.

Ensemble clustering algorithms were applied also for semi-supervised classification[8][9] are based on the hypothesis is more accurately for noisy data to reflect the actual similarity between different objects. They propose a Co-association Matrix (CM) based on the outputs of different clustering algorithms and use this as a similarity matrix in the regularization framework.

Berikon et al[10] use the same idea in the semi-supervised regression method. They combine graph Laplacian regularization and cluster ensemble methodologies. To accelerate the calculation, they apply the low-rank decomposition of the CM.

Our method is different. We only assume that the groups, which were built by the identical points in the categorical space, are quite pure. Moreover, we do not integrate the clustering matrix with any classification algorithms; instead we classify the objects based on the groups’ classified members.

Abdallah et al [11][12] developed a distance function based on ensemble clustering and use it within the framework of the *k-nearest* neighbor classifier and then improve selecting sampling for unsupervised data to be labeled by an expert. Additionally Abddallah and Yousef [13] integrated EC within Decision Trees, K Nearest Neighbors, and the Random Forest classifiers. The results obtained by applying EC on 10 datasets confirmed the hypothesis that embedding the EC space would improve the performance and reduce the feature space dramatically.

A recent study by Yousef et al [14] used EC classification comparing it to two-class SVM and one-class classifiers applied on sequence plant microRNA data. The results show that K-Nearest Neighbors-EC (KNN-ECC) outperforms all other methods. The results emphasize that the EC procedure contributes to building a stronger model for classification.

Several experiments were conducted in order to evaluate the performance of the suggested method. We tested it over 10 datasets and compare its results to the *k nearest* neighbors, decision trees and random forest classification algorithms. The results show that the new algorithm using the ensemble clustering was superior and outperforms the other baseline algorithms on most of the datasets.

# **Ensemble Clustering Technique**

This section describes the ensemble clustering technique that we use in this research. The basic algorithm assumes that points belonging to the same cluster are more similar than points that fall in different clusters. In real-world data, this assumption may not always hold, as illustrated in the following example In this example the data includes two classes (circles and diamonds). ~~Suppose that~~ If we cluster ~~this~~the data into two clusters, then ~~we will get that~~ the left cluster will include two types of classes and the right one ~~is pure (i.e.,~~  will still have all the points from the same class~~)~~.

To this end, we decided to run the clustering algorithm several times. Points belonging to the same cluster in the multiple runs will define a and will be classified to same class.

## **The Ensemble Clustering Categorical Space**

Here we describe how we transform the original data into the EC categorical space using the clustering method *k-*means. Let, be a set of labeled observations ~~that~~ used as training data, and A a set of unlabeled data. First, the algorithm will construct , where is a dataset combining and (i.e., ), then the algorithm runs the k-means clustering algorithm several times with different values of (we refer it to *nmc* = number of clusters) and ~~constructing~~builds the clustering matrix . is a matrix where the row consists of the clustering results of the object in . See Table 1 for an example.

The end result is that each is transformed into a new sample with categorical values. The dimension of the xi\* is *k.* Please note that one needs to take into account the categorical distance when applying similarity between two samples in the new categorical space. If in a specific run of k-means two samples or more have the same value then they were put in the same cluster, otherwise they were in different clusters. See Table 1 for an example of 20 samples with *k*=11. We record the results from *k*=2 as with *k*=1 – all the samples are placed in one cluster.

Table 1: EC space for 20 samples and number of cluster (nmc) of 11. First column is the sample name, second column is the results of assigning k-means of each sample into two clusters (c0 and c1), the third column is the result of assigning k-means for each sample into 3 clusters etc.

|  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| **Sample/k** |  **2** |  **3** |  **4** |  **5** |  **6** |  **7** |  **8** |  **9** |  **10** |  **11** |
| **sample 1** | c0 | c2 | c3 | c2 | c2 | c4 | c5 | c4 | c4 | c5 |
| **sample 2** | c0 | c0 | c3 | c3 | c2 | c4 | c4 | c4 | c4 | c2 |
| **sample 3** | c0 | c2 | c2 | c4 | c5 | c5 | c6 | c6 | c6 | c6 |
| **sample 4** | c1 | c0 | c0 | c3 | c3 | c2 | c2 | c3 | c3 | c3 |
| **sample 5** | c0 | c0 | c3 | c3 | c2 | c2 | c4 | c2 | c2 | c2 |
| **sample 6** | c0 | c2 | c3 | c2 | c4 | c4 | c5 | c4 | c4 | c5 |
| **sample 7** | c0 | c2 | c3 | c2 | c4 | c4 | c5 | c5 | c5 | c4 |
| **sample 8** | c0 | c2 | c2 | c4 | c4 | c5 | c6 | c6 | c6 | c6 |
| **sample 9** | c1 | c0 | c0 | c3 | c3 | c2 | c2 | c3 | c3 | c3 |
| **sample 10** | c0 | c2 | c3 | c2 | c4 | c4 | c5 | c5 | c4 | c5 |
| **sample 11** | c0 | c2 | c2 | c2 | c4 | c5 | c6 | c5 | c5 | c4 |
| **sample 12** | c0 | c2 | c2 | c2 | c4 | c5 | c6 | c5 | c5 | c4 |
| **sample 13** | c0 | c2 | c2 | c2 | c4 | c5 | c6 | c5 | c5 | c4 |
| **sample 14** | c0 | c2 | c3 | c2 | c2 | c4 | c5 | c4 | c4 | c5 |
| **sample 15** | c0 | c2 | c2 | c2 | c4 | c5 | c6 | c5 | c5 | c4 |
| **sample 16** | c0 | c2 | c3 | c2 | c4 | c4 | c5 | c5 | c4 | c5 |
| **sample 17** | c0 | c2 | c3 | c2 | c4 | c5 | c5 | c5 | c5 | c4 |
| **sample 18** | c0 | c2 | c3 | c2 | c2 | c4 | c5 | c4 | c4 | c5 |
| **sample 19** | c0 | c0 | c3 | c3 | c2 | c2 | c4 | c2 | c2 | c2 |
| **sample 20** | c0 | c2 | c2 | c2 | c4 | c5 | c6 | c5 | c5 | c4 |

Figure 1: The workflow for creating the EC categorical space based on the k-means clustering algorithm. The original data is the input to the workflow. The outcome is a new dataset named EC data in a categorical space with dimension k. the sign << indicates that k is dramatically smaller than the original data dimension N.

 ***EC Transformation***

**Input:**

E(*l*,N) : *x1 , x2,…,xl* Data consists of *l* samples in N dimension(features)

*k*: number of clusters

Create empty matrix *cMat* with *l* rows (number of samples) and *k* columns.

**Algorithm:**

For each *nmc in {1,2,3,…,k}* do*:*

 cMat{:,*nmc*} = k-means(E, *nmc*); assign for each sample *xi* a cluster c0,c1,..,ck-1

 (see Table 1 for an example of cMat)

Algorithm 1: EC transformation algorithm. The k-means clustering algorithm is used.

## **Reduction of the EC sample**

The new categorical data that results ~~of~~from applying the EC transformation (*Algorithm 1*) consists of *l* samples with *k* categorical features. As a results, the feature space is reduced dramatically, and the new dimension *k* is much less that the original data dimension (k<<N in Figure 1). More interestingly, the new EC data sample dimension can also be reduced. Samples or points that share the same cluster all over the *k* iteration of *k*-means are consider to be one point. For example, in Table 1, sample 11, sample 12 and sample 20 have the same categorical values. The vector space that represents those 3 points is =(c0, c2, c2, c2, c4, c5, c6, c5, c5, c4), additionally, as a result, the points (samples) sample 1 and sample 18 have the same values and can then be represented by and reduced to one point. The new EC samples then become redundant and can be represented by .

We have iterated all over the points in the EC data and keep the representor for each group.

Note that, the set contains labeled and unlabeled data, and as a result the groups may contain labeled and unlabeled objects. Generally, there are four possible cases for the objects that were grouped together:

1. All the objects are classified as the same class: in this case the group also will be classified as the class of its objects.
2. All the objects are classified but their classes are different: here the group will be classified as the majority class.
3. Some of the objects are classified and the rest are not: the same as in (2).
4. Not all the objects are labeled: in this case, the group will be an unclassified group.

To this end, we define a purity measurement for a group in order to evaluate the grouping process. The purity measurement is based mainly on the probabilities of the labeled objects as follows:

where denotes group that was represented by vector in the matrix , denotes the number of the members, , and denote the probability of class in group . As can be seen, equals 1 when the group is pure and for the lowest purity, that will decrease as the number of the classes increases.

# **Ensemble Clustering Based Classifier**

In this section we describe our new classifier approach, named GrbClassifierEC. The pseudo code of the algorithm is presented in *Algorithm 2*. The main goal of the classifier is to generate a unique EC sample from the generated EC samples, which is the representative set of EC samples. Next, for each EC sample, we need to check the distribution of the labels in its original group.

***Grouping based classifier***

**Input:**

 a matrix with the ensemble clustering results.

E(*l*,N) : *x1 , x2,…,xl* Data consists of *l* samples in N dimension features)

*k*: number of clusters

Create empty matrix *cMat* with *l* rows (number of samples) and *k* columns.

**Algorithm:**

1. Create the based on the EC results.
2. For each :
	1. Repeat until stopping criteria satisfies:
		1. Select labeled representor .
		2. Assign the label of to all the unlabeled members.
	2. Classify all the unlabeled members by the majority class that they have.
	3. Calculate the
	4. The accuracy for each unlabeled member will be the same as for the group purity.
3. Return the labeled dataset.

d

Algorithm 2: Our new approach for classification-based EC is to group the EC-based Classifier (ClassifierEC).

# **Experiments on Numerical Datasets**

To evaluate the merit of the new classifier GrbClassifierEC we compared its results to the k-nearest neighbors, decision trees and random forest classification algorithms. We tested it over 10 datasets and we compared the performance for each algorithm. The results show that the new algorithm using the ensemble clustering was superior and outperforms the other baseline algorithms on most the datasets.

# **Datasets**

The data ~~is consisting~~consists of microRNA precursor sequences, and each sequence ~~consists~~is made up of 4 nucleotide letters {A,U,C,G,}. The length of each precursor sequence is about 70 nucleotides. The source of this data is miRbase[15]. Part of the data we have used has was from other different studies[16,17], including our [13].

One simple way of representing sequences that consist of 4 nucleotide letters is by employing the k-mers frequency. The -mer counts in a given sequence were normalized by the length of the sequence.

Our features ~~are including~~include k-mer frequencies, other distance features that ~~just~~were recently ~~was~~ suggested by Yousef et al (2019) (still not published), and secondary features suggested suggest by [18]. Many additional features describing pre-miRNAs have also been proposed [19] and are included in the feature set that numbers1038 features.

The main data consists of information from 15 clades (Table 2). The *Homo sapiens* sequences were taken out of the data of its clade Hominidae. The homology sequences were removed from the dataset and only one representative was kept. One can generate about 256 datasets by considering a pair of two clades including itself. We selected 10 datasets at random from those listed in Table 3.

Table 2: The table shows a list of clades used in the study. The first column represents the name of the clade, the second column the number of pre-cursors available on miRBase, and the third column the number of precursors after preprocessing the data.

|  |  |  |
| --- | --- | --- |
|  Data set | Number of Precursors | Number of Unique Precursors |
| Hominidae  | 3629 | 1326 |
| Brassicaceae | 726 | 535 |
| Hexapoda | 3119 | 2050 |
| Monocotyledons (Liliopsida) | 1598 | 1402 |
| Nematoda | 1789 | 1632 |
| Fabaceae | 1313 | 1011 |
| Pisces (Chondricthyes) | 1530 | 682 |
| Virus | 306 | 295 |
| Aves | 948 | 790 |
| Laurasiatheria | 1205 | 675 |
| Rodentia | 1778 | 993 |
| *Homo sapiens* | 1828 | 1223 |
| Cercopithecidae | 631 | 503 |
| Embryophyta | 287 | 278 |
| Malvaceae | 458 | 419 |
| Platyhelminthes | 424 | 381 |

 Table 3: Ten datasets. The first column shows the name of the first clade positive data, and the second column the second clade negative data.

|  |  |
| --- | --- |
| Positive Data  | Negative Data |
| Aves | Embryophyta |
| Cercopithecidae | Malvaceae |
| Embryophyta | Laurasiatheria |
| Fabaceae | Nematoda |
| Hexapoda | Aves |
| Laurasiatheria | brassicaceae |
| Malvaceae | Fabaceae |
| brassicaceae | Hexapoda |
| hominidae | Cercopithecidae |
| Monocotyledons  | homoSapiens |

# **Reduction of the EC SAmple**

For each unique point we measure its size, equal to the number of times this unique point appears in the EC data. For example, in Table 3, we have 305 unique points with size 1. All these points appear once in the data. In addition, we have 68 unique points. If each one appears twice in the data, then each one is size 2. There are 22 points with size 3 – each of these 22 unique points appears 3 times in the data. Note that the labels are not included in the EC data This means that the group of points at the EC space can have different labels associated with the original points and still share the same group.

Table 3 shows the output of the EC procedure with *k*=30 applied on the data Cercopithecidae vs Malvacea that contains 894 examples (points). The table also shows that the EC data has 449 unique points, a 50% reduction in the size of the original data (449/894=0.5).

Table 4: The data Cercopithecidae vs Malvacea with k=30. The total number of samples (points) is 894 which is the sum of column #Points. The size of the unique points is the sum of columns “Unique Points” which is 449. #Points is multiplication of Size and Unique Points. Ratio Unique Points is the #Unique Points/Total #Points while Ratio All is #Points/Total #Points.

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| Size | Unique Points | #Points | Ratio Unique Points | Ratio All |
| 1 | 305 | 305 | 67.929% | 34.116% |
| 2 | 68 | 136 | 30.290% | 15.213% |
| 3 | 22 | 66 | 14.699% | 7.383% |
| 4 | 18 | 72 | 16.036% | 8.054% |
| 5 | 11 | 55 | 12.249% | 6.152% |
| 6 | 5 | 30 | 6.682% | 3.356% |
| 7 | 5 | 35 | 7.795% | 3.915% |
| 10 | 4 | 40 | 8.909% | 4.474% |
| 13 | 3 | 39 | 8.686% | 4.362% |
| 8 | 3 | 24 | 5.345% | 2.685% |
| 9 | 2 | 18 | 4.009% | 2.013% |
| 29 | 1 | 29 | 6.459% | 3.244% |
| 14 | 1 | 14 | 3.118% | 1.566% |
| 31 | 1 | 31 | 6.904% | 3.468% |
| Total | **449** | **894** |  |  |

Figure 2 shows the distribution of the group size for *k*=30 and *k*=50, and clearly indicates that as *k* increases, the number of groups with size 1 also increases. The expectation is that the number of groups of size of 1 should be the same as the number of the original number of samples as we increase the value of k. In other words, each sample will be hosted in one cluster. This actually raises a scientific question: what is the optimal value of *k* that will yield in improving the performance of the classifier, or more specifically, capture the nature of the data in terms of clusters.

Figure 2:Distributaion of the groups samples (points) size comparing nmc=30 and nmc=50.

## **Model Performance Evaluation**

We tested a different number of EC clusters ranging from 10 to 100 iterated 10 times. For each level, we performed 100 iterations with equal sample size, and then calculated the mean of each performance measurements described below.

For each established model we calculated a number of performance measures for the evaluation of the classifier such as sensitivity, specificity, and accuracy according to the following formulas (TP: True Positive, FP: False Positive, TN: True Negative, and FN False Negative classifications):

##  **Results**

We also conducted a study comparing the new classifier GrbClassifierEC with the other known classifiers such as k-nearest neighbors, decision trees and random forest classifiers. The results are presented in Table 5. The results clearly show that the performance of the suggested classifier GrbClassifierEC was superior.

Figure 3 shows the performance of different classifiers at different levels of training percentage of the data. The results of EC refer to our own GrbClassifierEC classifier. We see that the performance is not significantly influenced by the size of the training part for the other classifiers while it does increase significantly for the GrbClassifierEC classifier, at the 39% level. In addition performance can be improved significantly if the training part is increased, as a function of the value of k in the EC transformation.

In terms of data reduction, Table 5 and Table 6 demonstrate that about 56% of the samples data are reduced in the EC space with a *k* value of 49 and 39% in the EC space with a *k* value of 30. The results demonstrate the advantage of our approach in reducing the size of the data, for dealing with big data.

Table 5 and Table 6 show the results of a comparison of the EC classifier with other classifiers applied on the whole feature space (named Regular Classifiers), and the performance of Random forest applied on the EC categorical data(EC-RF).

Figure 3: The accuracy of the classifiers over different level of sample training size.

Table 5 presents results with a *k* value of 49, while Table 6 presents results with *k* 3. Interestingly, EC Classifier outperforms all the other approaches while using just 56% in average of the data (see ratio column), while the regular classifiers use 80% of the data for training. The EC classifier outperforms the standard approaches by 9% for the DT, 6% for the KNN, 8% for the random forest applied on the EC sample, and by 3% for the regular random forest.

Table 5: GrbClassifierEC: -EC classifier results with a k value of 49 compared to Random forest applied on the EC samples and results for regular classifiers applied on the original data (K is number of clusters).

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **Data/Performance** | **Data Info** | **EC Classifier**GrbClassifierEC | **Accuracy Difference** | **EC-RF** | **Regular Classifiers** |
| **#Sample** | **#EC\_Samples** | **ratio** | **Sensitivity** | **Specificity** | **F-measure** | **Accuracy** | **EC Random Forest** | **Random Forest** | **DTT** | **KNN** | **Sensitivity** | **Specificity** | **Accuracy** | **AccDT** | **AccKNN** | **AccRF** |
| Aves vs Embryophyta | 1068 | 726 | 68% | 0.97 | 0.92 | 0.97 | 0.96 | 0.02 | 0.01 | 0.05 | 0.02 | 0.84 | 0.97 | 0.93 | 0.91 | 0.93 | 0.95 |
| Cercopithecidae vs Malvaceae | 894 | 593 | 66% | 0.98 | 0.97 | 0.98 | 0.98 | 0.08 | 0.05 | 0.10 | 0.07 | 0.84 | 0.94 | 0.90 | 0.88 | 0.91 | 0.93 |
| Embryophyta vs Laurasiatheria | 953 | 652 | 68% | 0.96 | 0.92 | 0.96 | 0.95 | 0.08 | 0.04 | 0.10 | 0.07 | 0.94 | 0.72 | 0.87 | 0.85 | 0.88 | 0.91 |
| Fabaceae vs Nematoda | 2642 | 1004 | 38% | 0.85 | 0.89 | 0.84 | 0.87 | 0.02 | -0.01 | 0.04 | 0.00 | 0.92 | 0.76 | 0.85 | 0.83 | 0.88 | 0.89 |
| Hexapoda vs Aves | 2840 | 2087 | 73% | 0.85 | 0.95 | 0.86 | 0.92 | 0.10 | 0.03 | 0.11 | 0.10 | 0.61 | 0.91 | 0.83 | 0.81 | 0.82 | 0.89 |
| Laurasiatheria vs Brassicaceae | 1209 | 570 | 47% | 0.93 | 0.93 | 0.94 | 0.93 | 0.05 | 0.01 | 0.05 | 0.02 | 0.86 | 0.90 | 0.88 | 0.89 | 0.91 | 0.92 |
| Malvaceae vs Fabaceae | 1401 | 749 | 53% | 0.69 | 0.87 | 0.68 | 0.82 | 0.16 | 0.05 | 0.15 | 0.12 | 0.84 | 0.22 | 0.67 | 0.67 | 0.70 | 0.77 |
| brassicaceae vs Hexapoda | 2584 | 870 | 34% | 0.84 | 0.96 | 0.84 | 0.93 | 0.02 | 0.00 | 0.03 | 0.01 | 0.97 | 0.74 | 0.92 | 0.90 | 0.93 | 0.94 |
| Hominidae vs Cercopithecidae | 1829 | 1059 | 58% | 0.72 | 0.91 | 0.73 | 0.86 | 0.15 | 0.09 | 0.20 | 0.14 | 0.25 | 0.87 | 0.70 | 0.66 | 0.71 | 0.76 |
| Monocotyledons vs HomoSapiens | 2625 | 1460 | 56% | 0.92 | 0.93 | 0.92 | 0.92 | 0.10 | 0.03 | 0.09 | 0.04 | 0.84 | 0.82 | 0.83 | 0.83 | 0.88 | 0.89 |
| **Average** |  |  | **56%** | **87%** | **92%** | **87%** | **91%** | **8%** | **3%** | **9%** | **6%** | **79%** | **78%** | **84%** | **82%** | **85%** | **89%** |

The results in Table 6 show that one ca reduces more the size of the data to reach 39% ration with *k*=30 and still get a reasonable result. The EC classifier outperforms DTT and EC-RF and KNN with 5%, 3% and 1% respectively, while RF outperforms it with 2%. More interestingly, that ration of the reduction is an indication about the data redundancy and the similarity of the original data points.

Table 6: GrbClassifierEC: EC classifier results with a k value of 30 compared to Random forest applied on the EC samples and results for regular classifiers applied on the original data. K is number of clusters. The section “Accuracy Difference” is EC Classifier-ACC of the other classifier. A positive value indicates that the EC classifier is better than the other corresponding classifiers. EC-RF is a random forest applied on the EC data, RF is a random forest applied on the original data. DTT is a decision tree while KNN is K- Nearest Neighbors applied on the original data.

|  |  |  |  |
| --- | --- | --- | --- |
| **Data/Performance** | **Data Info**  | **EC Classifier**GrbClassifierEC | **Accuracy Difference**  |
| **#Sample** | **#EC\_Samples** | **ratio** | **Sensitivity** | **Specificity** | **F-measure** | **Accuracy** | **EC-RF** | **RF** | **DTT** | **KNN** |
| **Aves vs Embryophyta** | 1068 | 513 | 48% | 0.86 | 0.94 | 0.85 | 0.92 | -0.01 | -0.03 | 0.02 | -0.01 |
| **Cercopithecidae vs Malvaceae** | 894 | 449 | 50% | 0.94 | 0.92 | 0.94 | 0.94 | 0.04 | 0.01 | 0.06 | 0.03 |
| **Embryophyta vs Laurasiatheria** | 953 | 493 | 52% | 0.94 | 0.83 | 0.94 | 0.91 | 0.04 | 0.00 | 0.06 | 0.03 |
| **Fabaceae vs Nematoda** | 2642 | 536 | 20% | 0.78 | 0.88 | 0.79 | 0.84 | -0.01 | -0.05 | 0.01 | -0.04 |
| **Hexapoda vs Aves** | 2840 | 1647 | 58% | 0.76 | 0.92 | 0.78 | 0.88 | 0.05 | -0.01 | 0.07 | 0.06 |
| **Laurasiatheria vs Brassicaceae** | 1209 | 406 | 34% | 0.89 | 0.88 | 0.89 | 0.88 | 0.00 | -0.04 | 0.00 | -0.03 |
| **Malvaceae vs Fabaceae** | 1401 | 451 | 32% | 0.55 | 0.80 | 0.53 | 0.73 | 0.07 | -0.04 | 0.06 | 0.03 |
| **brassicaceae vs Hexapoda** | 2584 | 542 | 21% | 0.77 | 0.95 | 0.78 | 0.91 | -0.01 | -0.03 | 0.01 | -0.02 |
| **Hominidae vs Cercopithecidae** | 1829 | 786 | 43% | 0.61 | 0.87 | 0.63 | 0.80 | 0.10 | 0.04 | 0.14 | 0.09 |
| **Monocotyledons vs HomoSapiens** | 2625 | 855 | 33% | 0.86 | 0.87 | 0.86 | 0.87 | 0.04 | -0.03 | 0.03 | -0.01 |
| **Average** |  |  | **39%** | **80%** | **89%** | **80%** | **87%** | **3%** | **-2%** | **5%** | **1%** |

# **Conclusion**

In this paper we demonstrated the advantage of the EC approach in reducing the feature space and also in reducing the data size. In addition, we proposed using the new GrbClassifierEC based on the EC data. Generally speaking, we shown that we are able to reduce the number of features dramatically to 5% or 3% (50/1038 = 0.048, 30/1038=0.0.28) and reduce the size of the data to 56% and 39%, and still achieve a similar performance level, or even outperform regular classifiers applied on the original data.. However, to achieve these results the computation times that the ES transformation algorithm requires, increase.

The main assumption was that points within the same cluster share common traits more than points within different clusters. Thus it may be more beneficial to represent objects based on the clustering space rather than the geometric space.

The approach suggested here is very useful for the field of big data that allows a reduction of the data to representative data, by taking into account the EC data. For future research we will need to suggest an algorithm that would pick the optimal value of k that and yield improved performance while reducing the size of the data considerably.

Our algorithm can be integrated with many other algorithms. In this research, we use only the k-means clustering algorithm with different k values. In future research, we propose several directions: (1) checking the effect of the clustering algorithm to build an ensemble clustering space. (2) finding poor clustering results based on the training data, (3) reducing the volume of the data by combining similar points based on the EC.

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